Project Description

The overall aim of this project is to develop a system that is capable of distributed, multi-agent planning and plan repair by autonomous agents. One specific area that we will look into is that of the amount of information that is exchanged in the process (i.e. privacy aspects).

As centralistic approaches to Constraint Programming have advanced the state of the art in centralistic planning, we will look at techniques from Distributed Constraint Optimisation and Satisfaction in designing our system.

Project Coordinators

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